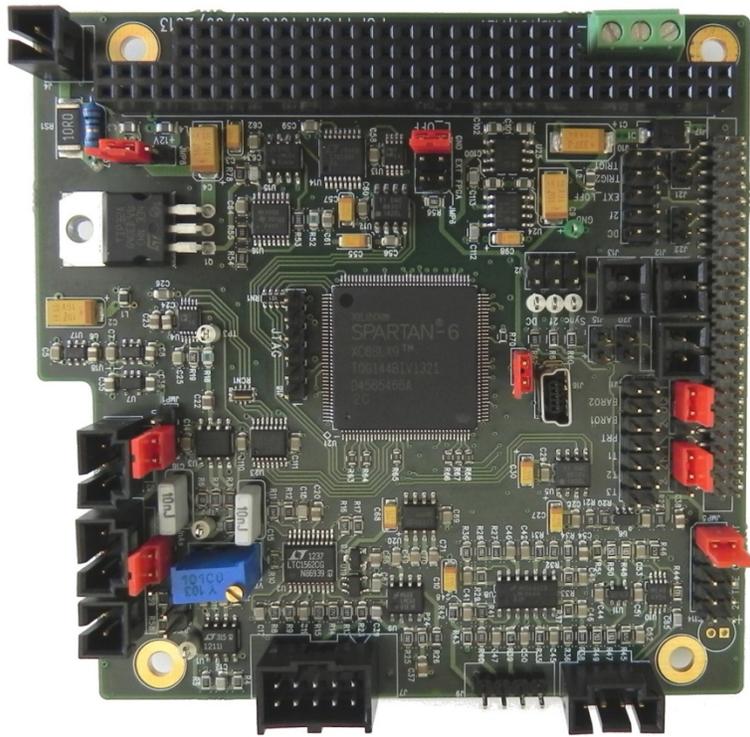




Port City Instruments, LLC
SINGLE-LINE SPECTROSCOPY SOLUTIONS

PCI-FPGA-1A

User Guide



(Rev C, V1.3)

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Document Change History

Rev #	Date	Changes
1.0	May, 2012	Initial Release. Rev A board.
1.1	November, 2012	Rev B board. New GUI Interface, scan waveform save option, tooltips, user capacitor for selection of 2f output time constant, USB power select jumper added.
1.2	November, 2013	Rev C Board. Native USB interface, +12V option added for higher voltage compliance for Interband Cascade lasers and Quantum Cascade lasers (to 10.7V, 800 mA).
1.3	March 2017	Corrected errors in Appendix B.

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1 Introduction

1.1 Company Overview

Port City Instruments, LLC provides scientific and engineering instrumentation and support services for industrial, university and government researchers working in the fields of single-line spectroscopy for gas detection. Products include tunable diode laser spectrometer controllers (board level and packaged), custom research-grade laser hygrometers and other laser-based gas sensors, and accessory boards for thermal control and pressure sensor conditioning. The company is currently located in Reno, Nevada, USA.

1.2 Product Overview

1.2.1 Description of the PCI-FPGA-1A circuit board

The PCI-FPGA-1A is a single-board, PC104 format second harmonic (2f) spectrometer controller for use with tunable diode lasers that operate CW at drive currents below 200 mA. It is based on a field programmable gate array (FPGA) interfaced to an on-board flash for storage of nonvolatile parameters.

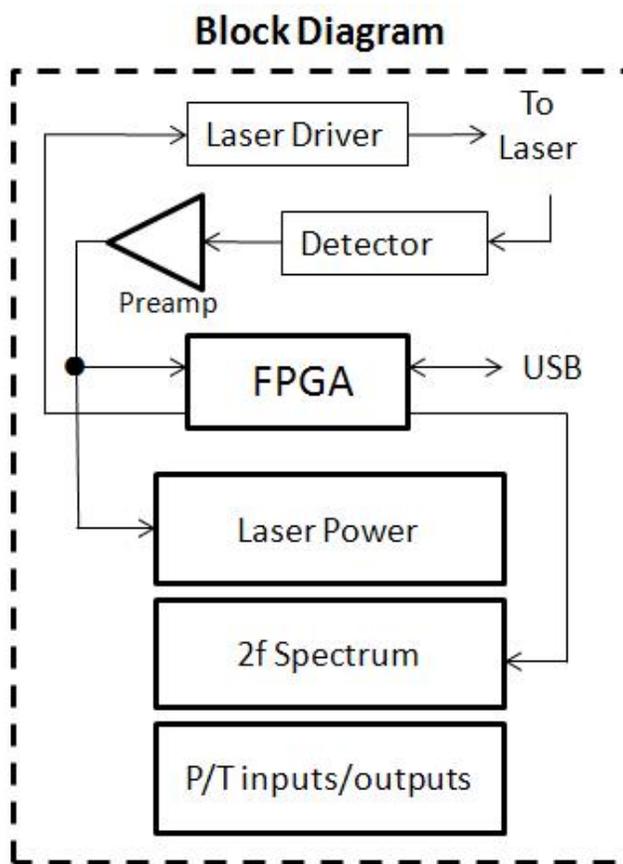
The board can also be used to control a laser for direct transmission operation by setting the 1f modulation amplitude to zero and monitoring only the DC channel output.

NOTE: This manual describes only the OEM board level product (-1A). Manuals for the related products are available in PDF format on the company website:
www.portcityinstruments.com

In addition to a laser current driver and detector signal processing electronics for generating 2f spectra, the board also contains bias and conditioning circuitry for common temperature sensors (thermistor and PRTD) and pressure sensors (amplified ratiometric sensors, and unamplified 0 - 100 mV output sensors). These environmental parameters enable the spectrum processing necessary to produce a gas concentration from the measured spectra.

The control board is designed as a continuous-sweep controller. The laser current is repetitively swept over a specified current range defined through parameters entered on a graphical user interface (GUI) running on a Windows PC.

The GUI is also used to define additional parameters, including but not limited to the following:



- The (sinusoidal 1f) wavelength modulation amplitude
- The laser sweep rate (0.1 Hz to 10 Hz)
- The 2f demodulation gain (1 - 100) and phase (0 - 360 degrees)
- The width of a laser OFF period at the start of each sweep

All parameters can be saved to on-board flash memory so that the system can be powered up in a known state without the need for a PC connection. This feature makes the board ideal for running "headless" gas sensors where automatic operation begins after each power up event.

All output data are supplied as analog signals within the 0 - 5 VDC range that can be monitored with any external data acquisition system capable of monitoring signals in this voltage range.

1.2.2 Package contents

The OEM circuit board package contains the following component parts:

- One PCI-FPGA-1A circuit board
NOTE: Always observe ESD precautions when handling!
- One mini-USB cable for connection to a Windows® PC
- Printout of flash parameters as shipped (these can be changed via the flash programming software available at www.portcityinstruments.com/downloads).

1.2.3 Specifications

PCI-FPGA-1A, Rev. C
1f Modulation Frequency: 31.4 KHz sine wave (adjustable over small range via flash programming interface)
FPGA-based 2f demodulation: 62.8 KHz (2f)
Auxiliary Inputs: 3 x Thermistor, 2 x Pressure, 1 x PRTD
Input Power: +5V DC (-0.1V, +0.2V) at 160 mA for DFB lasers Optional +5V/+12V configuration for ICL and QC lasers (custom only) Note: This does not include the laser current which will vary with the laser.
Operating Temperature: -25C to +75 C
Output signal ranges: 0-5V (all analog signal outputs)
Output signal resolution: 16 bits into Analog R/C
Spectrum noise levels after R/C (electrical only): +2 LSB
Laser Current Range: 0 - 200 mA (DFB), up to 10.7V, 800 mA IC/QC
Detector Compatibility: InGaAs, InAs, Si, HgCdTe (PV only)
Demodulator Gain: 1 - 100 (selectable via GUI)
Demodulator Output Time Constants: 4.1, 1.9, 1.3, 0.6 ms (via jumpers), and user defined (via cap)
Dimensions: 3.9" x 3.8" (PC/104 format mounting holes)

1.3 User Guide Overview

This user guide provides detailed information on how to set up the control board hardware and how to configure the on-board flash for use as a standalone 2f spectrometer controller.

As this product is an OEM circuit board and not a fully-packaged laboratory instrument, it is assumed that the user is familiar with the proper handling of ESD sensitive devices and will take the necessary precautions to protect the board and its components from electrostatic discharge.

Additional notes are provided specifically for the Diamond Systems Helios™ CPU board, which contains on-board analog I/O. Using this CPU board, a complete and rugged 2f spectrometer controller with 16-bit data acquisition can be built that is suitable for both laboratory and field use.

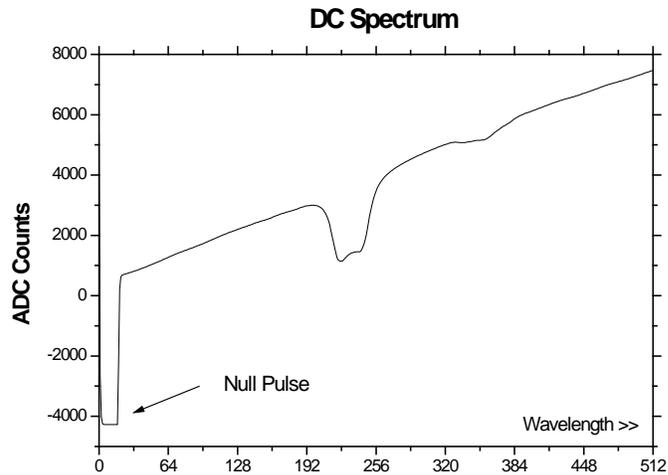
1.3.1 Special Terminology

There are certain terms used in this manual that may be different from other descriptions of the spectra produced by a second harmonic spectrometer. We will refer to:

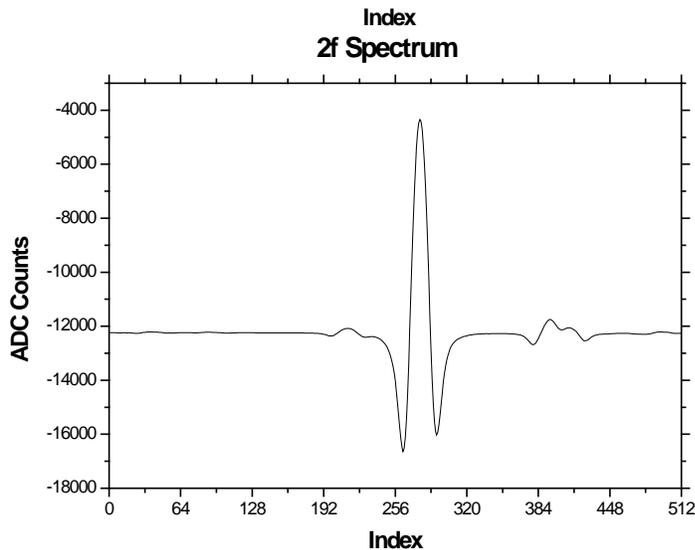
- **The second harmonic spectrum as the "2f" spectrum.** The 2f spectrum is the second harmonic spectrum produced by demodulation at twice the 2f modulation frequency within the FPGA. Because of signal processing time within the FPGA, the 2f spectrum is delayed in time relative to the DC spectrum. Two separate trigger pulses are output from the board to precisely measure this time delay, which is a function of the "Bandwidth" setting described in section 3.2.
- **The direct transmission spectrum as the "DC" spectrum.** The direct transmission spectrum is also called the laser power spectrum, and simply

represents the laser power at the detector (DC-coupled) as the laser current is swept in wavelength by the controller.

Below is an example of a spectrum pair (2f and corresponding DC = Laser Power) recorded with the PCI-FPGA-1A controller board using a 0-5V data acquisition system scaled to a counts range of -32768 to +32767 (i.e. 16 bit signed integers). The vertical offset in the DC spectrum is fixed and is implemented to obtain a slightly higher bit resolution on the digitized data. The vertical offset in the 2f spectrum is adjustable via the GUI interface and normally set to accommodate the asymmetric 2f line shape (negative lobes are smaller in amplitude than the positive peak).



Typical DC spectrum after A/D conversion. The null pulse provides the DC signal chain "zero" output in the absence of laser light, and is especially useful for situations where ambient stray light or sunlight can reach the detector.



There is a small temporal offset in the 2f spectrum due to processing within the FPGA. Separate trigger outputs allow this offset to be measured continuously. Phase and gain of the 2f demodulator are adjustable via the GUI.

2 Software Installation

2.1 Software files

Configuration of the PCI-FPGA-1A board is handled through a simple graphical interface that can be downloaded from our website at: <http://www.portcityinstruments.com/downloads>. Follow the instructions below to install the software on a compatible PC (running Windows™ XP (service pack 3), Vista, or Windows 7).

2.1.1 Software installation

To install the software, complete the following steps:

1. Download the Rev C flash programming software file from the following link:

<http://www.portcityinstruments.com/downloads>

(locate the "Rev C Programming Interface" link on the above web page). A ZIP file contains the installer and associated programs for the flash programming graphical interface. The file name is PCI_FPGA_RevC_Install.zip.

2. Unzip the file PCI_FPGA_RevC_Install.zip to extract the GUI application files. We suggest making a new folder on your hard drive (e.g. C:/PCI_FPGA) and copying the ZIP file to this new folder prior to extraction so that the files are in a known location.
3. Double-click the file PCI_FPGA_RevC_setup.exe to install the application.
 - You may be asked to allow Windows to continue with installation without a verifiable certificate. Click **OK** to allow the installation to proceed.
 - A new program will be added to the program list, which can be accessed via the Start button (Start > All Programs > Port City Instruments, LLC > PCI-FPGA-1A Controller).
4. Right click the new program and select **Send To**, then select **Desktop (create shortcut)** to place the program icon on your desktop for easy future access.

NOTE: on some older XP systems we have reports that the install process ends with an error message and asks for permission to send a report to Microsoft. However, the application does install and run correctly despite this message. If you see this message, simply ignore it. Check to see if the application appears in the Start > All Programs menu. Contact us if you have a problem with the installation.

5. Apply +5VDC power to the PCI-FPGA-1A board via the green screw terminal connector on the side of the board (see section 3.2 for the location, and make sure to connect the ground (GND) and +5V wires properly ... do not make a connection to the +12V terminal at this point). If the board is installed on a PC104 stack, it can receive power via the stackthrough connector in which case make no connections to the screw terminal connector on the board.
6. Connect the USB cable that was supplied with the board to the PCI-FPGA-1A board's mini-USB connector.

Windows should automatically recognize that new hardware has been detected and install the USB driver. Double click the program icon to begin programming.

At this point, all software is installed. The next step is to configure the FPGA's onboard flash.



DO NOT YET CONNECT A LASER TO THE BOARD!!

It is critical to confirm that the flash is configured properly for the type of laser being used or irreversible damage to the laser can result. We have provided a "dummy" laser that can be used to confirm proper laser scan parameters before connection of a real laser, and strongly recommend that the following steps be carried out before laser connection.

3 FPGA Flash Configuration

3.1 Warning



DO NOT CONNECT A LASER TO THE BOARD UNTIL YOU HAVE FINISHED CONFIGURING THE FPGA FLASH!

It is critical to confirm that the flash is configured properly for the type of laser being used or irreversible damage to the laser can result. We have provided a "dummy" laser that can be used to confirm proper laser scan parameters before connection of a real laser, and strongly recommend that the following steps be carried out before laser connection.

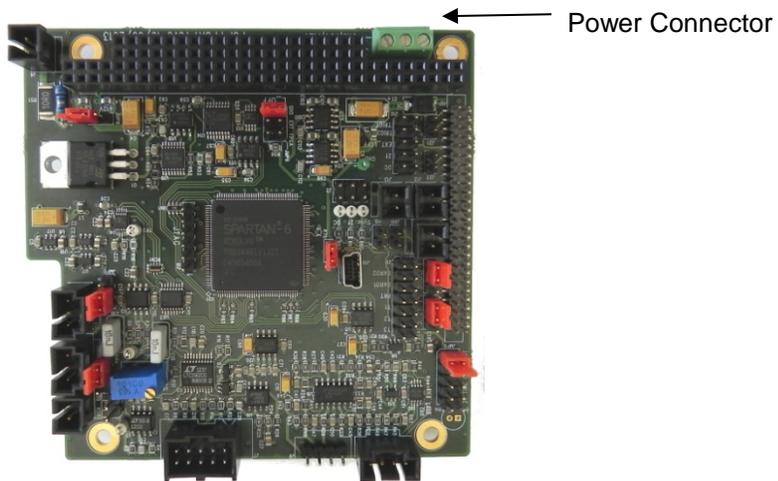
3.2 Configuration instructions

To configure the FPGA flash, complete the following steps:

1. Power up the PCI-FPGA-1A board. +5VDC power can be supplied to *either* the auxiliary +5V input *or* via the PC104 bus, but not both.

See below for the location of the auxiliary power input connector (polarity is indicated on the board silkscreen label).

NOTE: The USB port cannot supply enough +5V power to run a laser or other circuit boards.



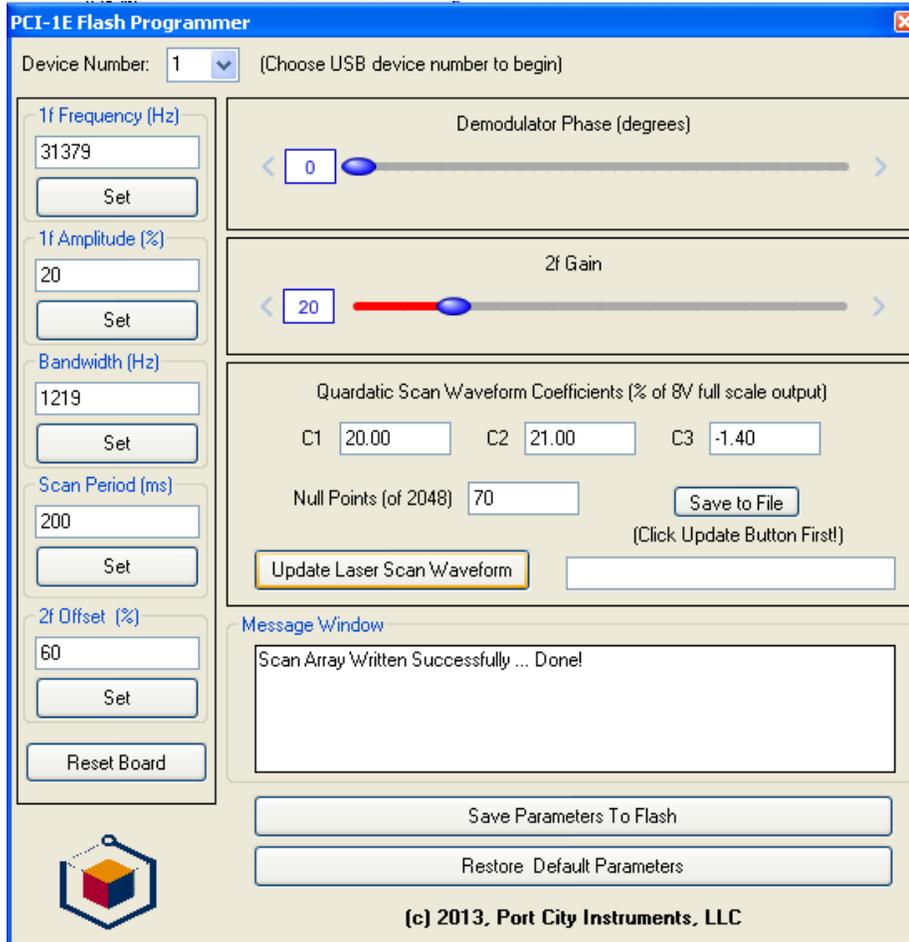
2. Make sure the USB cable is connected to the computer and that the software installation steps described in Chapter 2 have been completed.
3. Launch the user interface by double-clicking the icon that you created on your desktop in the Section 2.

Or navigate to the program from Start > All Programs > Port City Instruments, LLC > PCI-FPGA-1A Controller.

Select a USB device number from the dropdown list at the top, left of the GUI.

- If you only have one PCI-FPGA-1A board connected via a USB port then there should be only one entry in the dropdown list (number "1").

- If there are multiple entries make sure to select the device number corresponding to the board being programmed. If in doubt, connect only one board to the PC at a time (recommended).
- Initial parameters are read from the FPGA flash and displayed in the Flash Control window. (Default parameters are programmed before shipping for a typical DFB laser.). A screen capture of the GUI with typical DFB laser settings is shown below.



- Change any parameter by typing a new value into the text box and clicking the **Set** button within each category.
- For the demodulator gain and phase, use the sliders. These update when the mouse button is released (for example, slide the blue dot to a new value using the mouse with the left button held down, then release the mouse button to activate the new setting).

NOTE: Changes to the laser scan waveform (parameters C1, C2 and C3) take about 3-4s to update as 2048 values have to be transferred to the flash. All other parameters update in (typically) well under 1s.

- Once all values have been set correctly from the GUI, click **Save to Flash** button to write the new values to the flash.

These values will be automatically restored at each power up and USB connection to a PC is not required unless you need to modify a parameter.

Read through the following description of each parameter so that you can set the board up properly for your laser.

Field	Description
Frequency (Hz)	<p>1f modulation frequency.</p> <p>This should generally be in the range 31,200 Hz to 31,600 Hz for compatibility with internal filters.</p> <p>Leave this at the factory default near 31.4 KHz unless there is good reason to deviate from that value (e.g. if you have other instrumentation that coincidentally uses this same frequency).</p>
1f Level (%)	<p>Peak-to-peak amplitude of the (sinusoidal) 1f modulation on the laser current.</p> <p>It is entered as a percentage of the maximum modulation amplitude possible, which is 1/4 of the maximum laser current (or 50 mA).</p> <p>Contact us if you need to change this current limit (e.g. for VCSEL lasers or other lower current lasers) after the board has been received.</p>
Bandwidth (Hz)	<p>Controls the bandwidth of software filters within the FPGA.</p> <p>The input detector signal is passed through a preamplifier configured for either an InGaAs detector or an InAs detector. An A/D converter digitizes the signal after the preamp where it is passed to the FPGA for processing.</p> <p>This setting should generally be left at the factory default near 1219 Hz.</p> <p>This setting also (partially) controls the temporal delay between the 2f spectral line and the corresponding direct transmission spectrum. (This delay is caused by the internal FPGA signal processing time.) Values too high or too low can cause "ringing" in the 2f spectrum, so experiment with this value carefully before changing it from the factory default.</p> <p>See the discussion for connector J10 for additional information on the 2f vs. DC spectrum temporal delay as a function of the bandwidth setting.</p>
Ramp Period (ms)	<p>Sets the base laser scan period in ms.</p> <p>The software adjusts this number to the closest hard setting that is available from the FPGA (eg. entering 200 ms for a 5 Hz laser sweep rate may produce a value of 196 ms).</p> <p>Valid values are from 10,000 ms (0.1 Hz rate) to 100 ms (10 Hz sweep rate). Contact us for faster scan rates (up to 50 Hz).</p>

Table continued on next page

Field	Description
2F Output Bias (%)	<p>Controls the voltage offset of the 2f spectrum and should generally be close to 60%.</p> <p>The output 2f spectrum from the FPGA cannot be zero based with a single 5V power supply system because the signal swings both positively and negatively relative to the baseline. The actual voltage offset is equal to 0.025 times the percentage offset entered here.</p> <p>For example, a value of 60% produces a (positive) voltage offset of $60 * 0.025 = +1.5V$. A value of 100% produces a voltage offset of +2.5V, which is centered within the 0-5V range of the system.</p>
Phase (degrees)	<p>Demodulator phase.</p> <p>Move the GUI slider to change the demodulator phase from 0 to 360 degrees. The correct setting for the demodulator phase, as with any lock-in-amplifier, is best determined experimentally by optimizing the polarity and amplitude of the 2f signal using an oscilloscope or real-time data acquisition with display.</p> <p>This setting is activated when the mouse button is released.</p>

Table continued on next page

Field	Description
Gain	<p>Demodulator gain. Use this slider to adjust the amplitude of the 2f signal. As with the demodulator phase, this parameter is best defined using a real-time spectrum display. This setting is activated upon release of mouse button.</p> <p>NOTE: Always ensure that the gain is low enough to keep the 2f signal on scale for the highest gas concentration that is expected.</p>
Ramp Coefficients (%)	<p>The laser scan waveform is defined by a quadratic whose coefficients are entered into C1, C2 and C3. These are the:</p> <ul style="list-style-type: none"> • constant (C1) • linear (C2) • quadratic (C3) <p>terms of the polynomial and are entered as a percentage of the maximum laser current (200 mA unless ordered with an alternate upper limit). Only use the quadratic term if the laser tuning characteristics have been determined (eg. using an etalon) and this parameter is known. In the normal case of a linear ramp, C1 is the laser scan starting current. C2 represents the range of the scan ramp. For example, if C1 = 25% and C2 = 25%, the laser scan would run from 50 ma (0.25 * 200 mA) to 100 mA (50 mA starting current, plus 0.25 * 200 = 50 mA ramp range). Values of C1 = 30% and C2 = 15% would produce a linear scan starting at 60 mA and ending at 90 mA (i.e. a 0.15 * 200 mA = 30 mA range), and so on. See Appendix B for an example. The Null pulse entry defines the width (in points) of a short period at the start of each sweep where the laser current is set to zero. The total laser scan ramp consists of 2048 points, and this value should generally be in the range 60-90 so that the interval is long enough to produce a flat bottom through the "DC" signal chain. Click Update Laser Scan Waveform to rewrite the new scan waveform to the onboard flash. Note the Message Window messages and wait for the process to complete before continuing (approximately 10s to write, another 10s to verify).</p>
Save to File	<p>Saves the waveform defined by C1, C2 and C3 to a disk file. There are three columns ordered as array element number (beginning at 1), raw DAC counts, and fraction of the full scale current. For example:</p> <pre> 1 13107 0.20000 2 13113 0.20009 3 13118 0.20017 </pre> <p>may be the first three lines of a typical output file (with no null pulse).</p>

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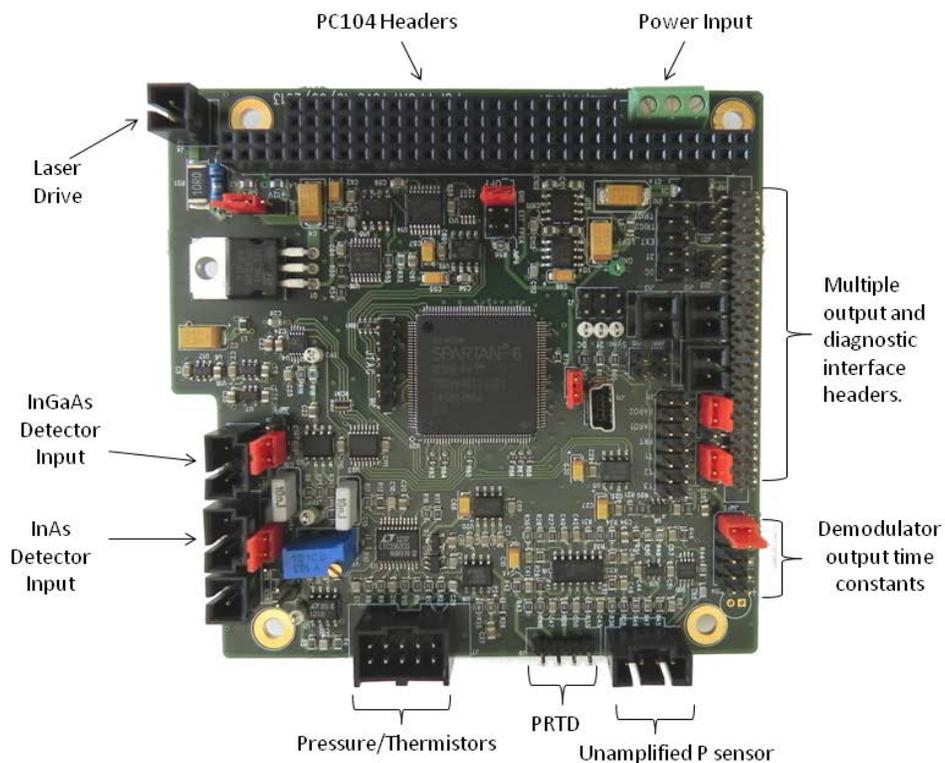
Field	Description
Message Window	Read-only display area showing various messages. In particular, this area shows when a new laser scan waveform has been successfully downloaded and verified. Watch this area each time you change the C1, C2, and C3 parameters and download a new scan waveform. Wait for confirmation before entering any new parameters for the flash.
Save Parameters to Flash	Preserves all of the configured settings and saves them to the flash drive. Be sure to execute this step each time parameters are changed if you want the system to power up in a known state each time.
Restore Factory Defaults	Resets the values in all fields to the default settings that existed when the software was originally shipped.
Reset Board	Hard reset of all board control parameters. Warning ... use this only if data in the flash has been corrupted and all other steps to correct the problem have failed. Requires reentry of each parameter (or follow by clicking the Restore All Default Parameters button to reset with default values).

4 Hardware Description

4.1 Hardware overview

The default configuration of the PCI-FPGA-1A board (as shipped) is for a standard distributed feedback (DFB) tunable diode laser (TDL) and an InGaAs detector. Some modifications may be necessary before operating lasers with higher current requirements (for example, ICL or QC lasers) or for the use of InAs or HgCdTe detectors. Please take a moment to examine the diagrams in Appendix A, which detail the function of each input and output pin on the circuit board, as well as the various jumper settings and their locations.

4.2 PCI-FPGA-1A board headers



All board connectors except for J17 are standard 0.10" pin spacing (J17 is 2mm pin spacing). Both latching and non-latching mating connectors can be used for connections to the board and are available from most of the electronics part suppliers as Molex part numbers (Digikey, Mouser, Jameco, Allied, Newark, etc.). For example, the mating connector for the 2-pin laser drive is Digikey part number WM2900-ND, and for the 3-pin detector connectors the Digikey part number is WM2901-ND.

The gain of the input preamp is set by the only potentiometer on the board shown in the photo above near the detector input connectors. This potentiometer should be adjusted to maintain an on-scale signal (<5.0V) at the output of the DC signal chain at the end of the laser scan once the laser is aligned to the detector.

If the laser power spectrum begins to flatten out at the right side of the DC signal channel output as viewed on an oscilloscope, reduce the preamplifier gain to bring the signal back on scale with some additional margin. See the description of JMP1 in section 4.2.3 for more details on InGaAs and InAs detector connections.

4.2.1 Connector Pinouts

See Appendix A for a complete pinout diagram for the circuit board. The sections below provide additional details for the various connectors and jumpers.

NOTE: All pin 1 positions (headers and jumpers) are identified on the circuit board with square solder pads on the reverse side of the board.

J1 and J3 are industry standard PC104 headers, and are provided on the board for compatibility with multiple board "stacks." The only pins used by the board are optional ground, +5V and +12V power (pins B1, B3 and B9 on the PC104 bus). Many websites contain pinout details for the PC104 bus, such as the one found at: http://pinouts.ru/Slots/Pc104_pinout.shtml

4.2.1.1 J3: Auxiliary +5V/+12 power inputs

Pin	Description
1	Power Ground
2	+5 VDC Auxiliary Power Input
3	+12VDV Auxillary Power Input

Power can also be supplied through the PC104 bus headers, in which case J3 should be left unconnected. Do not power the board through both J3 and the PC104 bus!

4.2.1.2 J4: Laser Drive

Pin	Description
1	Laser Cathode (-)
2	Laser Anode (+)

Laser drive connections.

NOTE: Check the silkscreen labels on the circuit board and **ensure that the laser is connected properly** (cathode to (-) pin, anode to (+) pin) before power up. Irreversible damage to the laser can result if the laser is connected backwards. Also make sure that the programmed laser current is within the capabilities of the laser being used. Currents exceeding the laser's specification can damage or destroy the laser.

4.2.1.3 J5: InGaAs Detector Input

Pin	Description
1	Ground (shield connection)
2	Detector Cathode (-)
3	Detector Anode (+)

Connect an InGaAs detector to J5 as shown on the board silkscreen (cathode to (-) pin, anode to (+) pin).

If you are using a shielded twisted pair or other cabling with a separate shield, also connect the shield to the pin labeled "S" on the board silkscreen.

For InGaAs detectors, the bias jumper (JMP1) should be set to "2.5". The InAs jumper (JMP2) should be OFF.

NOTE: It is possible to connect an InGaAs detector with zero bias (JMP1 in "0" position), but in this case the detector connections must be reversed at J5 and the DC spectrum polarity will be the opposite of the 2.5V reverse bias case.

4.2.1.4 J6: InAs Detector Input

Pin	Description
1	Ground (shield connection)
2	Detector Cathode (-)
3	Detector Anode (+)

Connect an InAs detector to J6 as shown on the board silkscreen (cathode to (-) pin, anode to (+) pin).

If you are using a shielded twisted pair or other cabling with a separate shield, also connect the shield to the pin labeled "S" on the board silkscreen.

For InAs detectors the bias jumper (JMP1) should be set to "0".

4.2.1.5 J7: Temperature, Amplified Pressure Sensor Inputs

Pin	Description
1	Thermistor #1 (+)
2	Thermistor #1 (Ground)
3	Thermistor #2 (+)
4	Thermistor #2 (Ground)
5	Thermistor #3 (+)
6	Thermistor #3 (Ground)
7	Amplified Pressure Sensor Output
8	Pressure Sensor Output Return (Ground)
9	+5.00V Reference for Amplified Pressure Sensor
10	Ground

Connector J7 allows connection of up to three thermistors and one amplified pressure sensor as shown above and in Appendix A. Most amplified pressure sensors provide ratiometric outputs that vary with the power supply.

Pin 9 of J7 provides a stable 5.00V reference voltage that can be used to power the pressure sensor, with the ground and output signals from the pressure sensor on pins 8 and 7, respectively.

The pressure sensor output value is provided on pin 6 of J11. Typical output ranges for this type of sensor are 0.25 to 4.75V, or 0.5 to 4.5V, but any sensor with an output in the 0-5VDC range can be used with the board, even if the power is provided externally (in which case leave pin 9 unconnected).

The thermistor transfer function is $R_t = (22.49 * V_{in} - 7.0) / (2.8112 - V_{in})$ where V_{in} is the output voltage on pins 10, 12 or 14 of J11 and R_t is the thermistor resistance in Kohm. Conversion to temperature requires knowledge of the thermistor R vs T curve, available from the manufacturer.

4.2.1.6 J8: Unamplified Pressure Sensor Input

Pin	Description
1	+10V Power (supplied by board)
2	Pressure Sensor (+) Output
3	Pressure Sensor (-) Output
4	Common

There are many 0-100 mV pressure sensors on the market that have a common mode voltage between the input power and the output signal connections. The PCI-FPGA-1A board provides a 10.0V power signal on pin 1 of J8. An on-board instrumentation amplifier circuit effectively eliminates the common mode voltage to produce an amplified output from the pressure on pin 4 of J11.

Nominal output range is 0 - 3.5V corresponding to the full range of the pressure sensor (e.g. 0 - 15 PSI, 0 - 1 Bar, etc.).

4.2.1.7 J9: PRTD Input

Pin	Description
1	PRTD Bias
2	PRTD (+)
3	PRTD (-)
4	Ground

J9 provides a small bias current for use with 1000 ohm PRTD platinum resistance temperature sensors. The output voltage from the sensor is provided on pin 8 of J11 with a transfer function of $R_{prt} = 495.52 * V_{in}$, where V_{in} is the voltage on J11 pin 8, and R_{prt} is the Pt sensor resistance.

Conversion to temperature can then be made using the manufacturer's data for the PRTD sensor element.

4.2.1.8 J10: Auxiliary Outputs

Pin	Description
1	Ground
2	Trigger #1 (synched with DC spectrum)
3	Ground
4	Trigger #2 (synched with 2f spectrum)
5	Ground
6	External Laser Off (LOFF)
7	Ground
8	2f Spectrum Output
9	Ground
10	DC Spectrum (laser power) Output

J10 provides the trigger and spectrum outputs from the DC and 2f signal chains.

There are two trigger outputs (3.3V amplitude, approximately 110 us in width).

- Trigger 1 is synchronized with the DC spectrum scan start.
- Trigger 2 is synchronized with the 2f spectrum.

The delay between these two trigger outputs is equal to the temporal delay between the DC and 2f spectra and can be used by the acquisition software to properly normalize the 2f spectrum to laser power. Approximate values for the delay between Trigger 1 and Trigger 2 as a function of the bandwidth setting are:

Bandwidth Setting (Hz)	Trigger Delay (ms)
250	82.0
500	41.5
750	27.0
1000	21.0
1250 (1219)*	16.4 (16.8)
1500	15.4
1750	13.4
2000	10.3

* (Suggested Bandwidth: 1219 Hz)

Also resident on J10 is an input for the LOFF signal, which enables (LOFF = 0V = ground), or disables (LOFF = +5V) the laser current.

Jumper JMP6 controls the source for the LOFF signal. This can either be jumpered in several ways:

- to ground directly (laser ON always). This is the GND position.
- to receive the signal from J10 pin 6 as an input to the board (EXT position)
- to be controlled from the FPGA (factory use only, do not shunt this position)

If the laser is not turning on and you believe it should be

Check the position of the JMP6 jumper pin 6 (LOFF) and make sure it is configured correctly. In the EXT position, pin 6 of J10 must be wired to a digital control line, or a switch.

4.2.1.9 J11: Auxiliary Temperature/Pressure Outputs

Pin	Description
1	Ground
2	No connection
3	Ground
4	Unamplified Pressure Sensor Output
5	Ground
6	Amplified Pressure Sensor Output
7	Ground
8	PRTD Output
9	Ground
10	Thermistor #1 Output
11	Ground
12	Thermistor #2 Output
13	Ground
14	Thermistor #3 Output

Thermistor, PRTD and pressure sensor outputs are provided on J11.

Transfer functions have been described earlier in the descriptions of the input connectors. They are also repeated in sections 4.2.4 (Thermistor conversions), and section 4.2.5 (Pressure sensor conversions (absolute P sensors)).

4.2.2 Other Connector Pinouts

Connectors J12-J15 and J20-J22 are used only when the PCI-FPGA-1A board is interfaced to the Diamond System Helios™ CPU board (with DAQ subsystem) having spare digital and analog input and output channels. These are provided for miscellaneous functions such as LED control, trigger signals, or other general use functions not related to operation of the PCI-FPGA-1A board itself. They pass through connector J17 and only have utility if connected to an external I/O system through J17 (and wired according to the Helios CPU board's DAQ connector).

4.2.2.1 J12: Utility Analog Output (Helios Vout0)

Pin	Description
1	Utility Analog Output
2	Ground

4.2.2.2 J13: Utility Analog Output (Helios Vout1)

Pin	Description
1	Utility Analog Output
2	Ground

4.2.2.3 J14: Utility Analog Output (Helios Vout2)

Pin	Description
1	Utility Analog Output
2	Ground

4.2.2.4 J15: Utility Analog Output (Helios Vout3)

Pin	Description
1	Utility Analog Output
2	Ground

4.2.2.5 J20: Utility Analog Input (Helios Vin10)

Pin	Description
1	Utility Analog Input
2	Ground

4.2.2.6 J21: Utility Digital Input (Helios DIO A2)

Pin	Description
1	Utility Digital Input
2	Ground

4.2.2.7 J22: Utility Digital Output (Helios DIO B2)

Pin	Description
1	Utility Digital Output
2	Ground

4.2.2.8 J16: Mini USB Connector for FPGA Setup

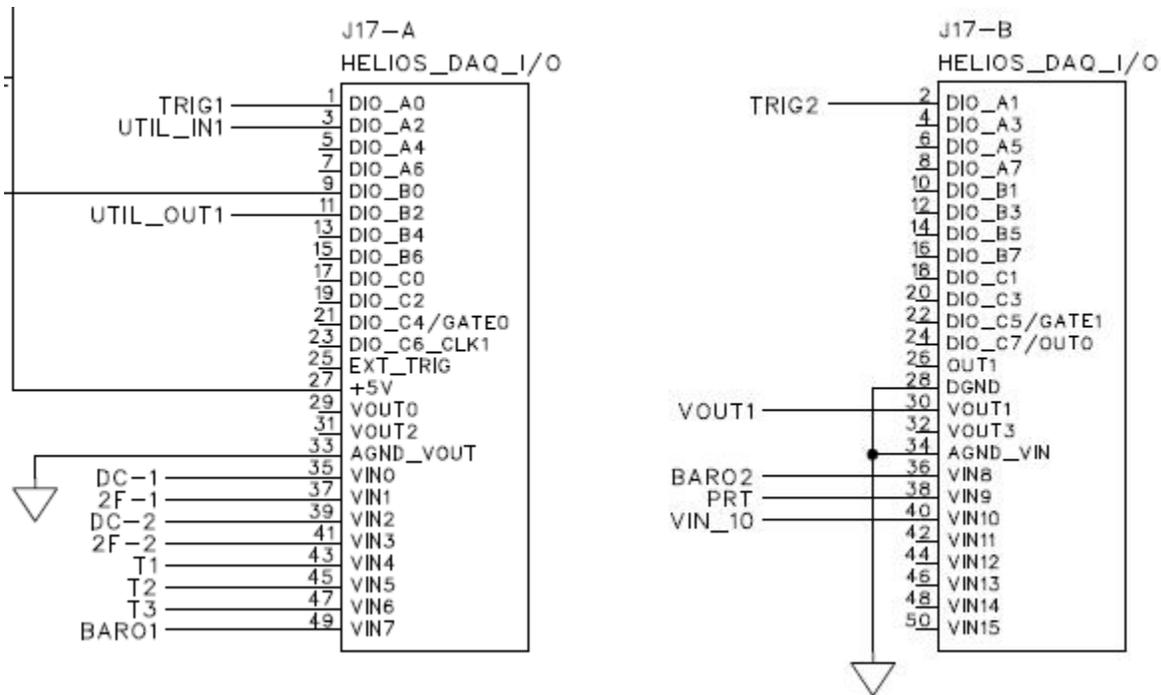
Pin	Description
1	Bus Voltage
2	D-
3	D+
4	ID
5	Ground

J16 is a mini-USB connector that is used for updating the laser control and demodulator parameters via the interface GUI. A mating cable is provided with the board, or any standard mini-USB cable can be used.

4.2.2.9 J17: 50-Pin I/O Header (alternate external I/O system interface)

J17 is used for direct interface to the Diamond Systems Helios™ CPU board (or any other external I/O system). The relevant pin connections are shown in the diagram on the next page simply to indicate how this interface is configured. This CPU board has onboard 16-bit I/O and can be used to build a complete 2f gas sensor with only a single +5VDC power supply and 2-board PC104 stack.

Please contact us for more information on operating the PCI-FPGA-1A board using the Helios™ CPU board.



4.2.2.10 J18: JTAG Connector

Do not make connections to J18. It is not user accessible. It is used to program the FPGA core.



Do not make connections to J18.

Any voltage applied to these pins can potentially damage the FPGA chip or corrupt the internal program.

4.2.2.11 J2: Diagnostics Header

Pin	Description
1	Trigger #1 (sync'd to DC spectrum)
2	2f Spectrum
3	DC (laser power) Spectrum

The Trigger1, 2f and DC spectrum signals on J2 are duplicates of the corresponding signals on J10, but with isolation resistors provided (4.75K for Trigger #1 and the 2f signal, 1K for the DC signal). These are useful for monitoring the signals with a high impedance device such as an oscilloscope during setup, laser alignment, etc. The signals on J10 are best used for direct connection to an external A/D converter, or when Trigger #2 (synchronous with the 2f signal) is needed.

4.2.2.12 J19: External Preamp Voltage Input

Pin	Description
1	V- (ground)
2	V+ (preamp output, 0-10V range only)

J19 is used only for a factory option that must be specified at order. It allows the board to accept the voltage output from an external preamplifier rather than receiving a detector input directly. Please contact us, or your distributor to order boards configured for this option. For direct detector input, make no connections to J19.

4.2.3 Jumper configuration

Please refer to the diagrams in Appendix A for the location of the jumper blocks described below. These drawings are also available as PDF files on the USB flash drive supplied with the board.

Default Jumper Positions		
Jumper	Function	Default Position
JMP1	Detector Bias	Shunt on pins 2-3 (2.5V reverse bias)
JMP2	InAs Detector Select	No shunt (pins open)
JMP3	2f signal pin connection to J17	Vin1 (DC)
JMP4	DC signal pin connection to J17	Vin0 (2f)
JMP5	2f channel output time constant select	4.1 ms
JMP6	LOFF digital laser ON/OFF control line	EXT
JMP7	USB power ON/OFF select	ON (USB +5V connected to board power)
JMP8	Laser drive power select	Shunt on pins 1-2 (+5V)
JMP9	Preamp voltage input select	No shunt (no connection to J19)

JMP1: Detector reverse bias jumper (shunt on pins 1-2 = 0V bias, shunt on pins 2-3 = 2.5V reverse bias). InGaAs detectors should be operated with the shunt in positions 2-3 (2.5V reverse bias) and with jumper JMP2 removed (open). InAs detectors should be operated with the shunt in positions 1-2 (0V bias), and with a shunt on jumper JPM2.

The default position is 2-3 for InGaAs detectors, 2.5V reversed biased.

NOTE: Photovoltaic HgCdTe detectors such as those sold by Vigo can generally be connected to the InAs input for use with mid-IR lasers such as interband cascade or quantum cascade lasers. Jumper for InAs detector input.

It is also possible to use an InGaAs detector with zero bias (JMP1 shut in positions 1-2, or "0 on the silkscreen"). In this case:

- JMP2 must be open (as always for InGaAs detectors)
- The InGaAs detector must be connected backwards relative to the silkscreen labels (ie. the detector cathode should be connected to the (+) pin and the detector anode to the (-) pin).

The DC spectrum with this connection scheme will be reversed in polarity relative to the normal reversed biased connection, as will the 2f spectrum (the demodulator phase for the 2f signal should be changed by 180 degrees on the GUI). It is recommended to always run an InGaAs detector with reverse bias if possible (JMP1 shunt in positions 2-3, JPM2 open, detector connections as per the board silkscreen).

JMP2: InAs detector jumper selector (ON = InAs connected, OFF = InGaAs connected). See comments for JMP1. This jumper should only be closed if an InAs detector is connected to J6, and JMP1 is shunted for zero bias.

The default position is OFF for InGaAs detectors.

JMP3: 2f output signal pin designation. This jumper is used, along with JMP4, to configure the connections at J17 for interfacing two PCI-FPGA-1A boards to the Diamond System's Helios™ CPU board. It should normally be left in Vin1 position (see description for J17, and Appendix A diagram). Together with JMP4, the 2f and DC outputs from the board can be transferred to alternate A/D input pins at J17.

The default position is Vin1 = J17 pin 2F-1.

JMP4: DC output signal pin designation. See comments for JMP3 (this jumper serves the same function but for the DC spectrum output).

The default position is Vin0 = J17 pin DC-1.

JMP5: 2f channel output time constant selector (0.6, 1.3, 1.9 and 4.1 ms). Apply a shunt to one of the five available time constant selections to set the low pass filter time constant for the demodulator output section. There is an open position for installation of a user-defined capacitor if a time constant >4.1 ms is required. The relationship is:

$$C(\text{Farad}) = \tau / ([2 * \pi * 2000])$$

where τ is the desired time constant in seconds, and $\pi = 3.141592$.

The default position is 0.6 ms (minimum value).

JMP6: LOFF (laser enable) source selector (on-board, external or FPGA). JMP6 provides options for controlling a digital line ("LOFF") that is used to enable, or disable, current to the laser. When LOFF is +5V the laser current is disabled, and when LOFF is tied to power ground, laser current is enabled. LOFF is pulled up to +5V via a 20K pullup resistor on the board. The three available jumper positions as indicated on the board silkscreen and in Appendix A (use PDF files for the Appendix A drawing supplied on the install USB drive for clearer views) are:

- **GND** – the LOFF is hard grounded which enables laser current at all times. Be very careful with this setting as the LOFF function is effectively disabled.
- **EXT** – the LOFF signal is provided externally either via J10 or J17 (if interfaced to the Diamond Systems Helios™ CPU board).
- **FPGA** - the LOFF pin is controlled by the FPGA itself (factory use only ... do not use this jumper option).

In general, JMP6 should be in the:

- EXT position if the board is being controlled via an external I/O system with an available digital line, or if a mechanical switch is used for laser ON/OFF.
- GND position for testing using a dummy resistor in place of the laser. Can also be used if it is certain no power-on transients at up to 200 mA will cause damage.

The default position is EXT.

JMP7: USB power selector. A shunt on these pins allows the UART interfaced to the flash chip to be powered by the same +5V source powering the board (PC104 bus, or the auxiliary power input). With this shunt removed the UART is powered by the USB cable (i.e. the PC the USB cable is connected to).

If programming a bare board (i.e. not on a powered PC104 stack, and no auxiliary power input) leave JMP7 open (no shunt).

If programming a board connected to auxiliary power or powered through the PC104 bus, apply the shunt to JMP7.

JMP8: Laser drive power source. Unless the circuit board is ordered for ICL or QC laser compliance capability, leave this jumper set for +5V laser drive power (default). With other component changes it is possible to use a +12V source (input via the auxiliary power screw terminal connector) to produce up to 10.7V compliance for QC lasers. Contact us for circuit boards configured for ICL or QC lasers.

The default position is +5V.

JMP9: Preamp input voltage select. This is a factory option only. The circuit board can be configured to accept the voltage from an external preamp rather than a detector input. This requires component changes on the circuit board and the shunt should be left in the "InAs" position for normal board operation. This position does not select InAs detector input as long as JMP2 is open ... JMP9 is used in conjunction with JMP2 for voltage input).

The default position is InAs.

4.2.4 Thermistor conversions

$R_t = (22.49 * V_{in} - 7.0) / (2.8112 - V_{in})$, where R_t is the thermistor resistance in Kohm and V_{in} is the output voltage provided by the PCI-FPGA-1A board. The useful range of thermistor resistances is between approximately 0.125 Kohm ($V_{in} = 0.325V$) to 488 Kohm ($V_{in} = 2.701V$). Outside of these ranges the change in V_{in} with respect to R_t is extremely large.

For a typical 10 Kohm @ 25C thermistor with a beta value near 3900, this represents a temperature range of roughly -45C to +165C, with larger errors at the extremes of the range (especially the high temperature end where R_t is very small). Make sure to use a thermistor with a resistance value within the above range for valid output values, and match it to the best performance over the full temperature range of the application.

4.2.5 Pressure sensor conversions (absolute P sensors)

- Amplified sensor: No conversion. The board outputs the sensor voltage from the absolute pressure sensor with no amplification or scaling.
- Unamplified 0 - 100 mV sensors: Linear output, 0 to $P_{max} = 0$ to V_{max} , where V_{max} is 3.5V (nominal) and P_{max} is the upper limit of the pressure sensor. Each pressure sensor should be calibrated with the board for precise determination of V_{max} and any DC offset that may be present.

4.2.6 PRTD conversion

$R_{prt} = 495.52 * V_{in}$, where R_{prt} is the resistance of the PRTD and V_{in} is the voltage output from the PCI-FPGA-1A board.

Conversion of R_{prt} to temperature can be done using the appropriate calibration curve for the PRTD being used.

5 Troubleshooting

No laser drive current present

1. Make sure the LOFF shunt is in the correct position as described in section 4.2.3 of this user guide, jumper JMP6. If this shunt is in the "EXT" position, an external digital line or a switch must be configured to ground the LOFF pin to enable laser current. In the GND position laser current is allowed to pass at all times (including at power up). The "FPGA" position should never be used (ie. shunt must only be on the EXT or GND positions).
2. GUI has not been programmed for a current range that is above laser threshold. Double check the currents programmed in the GUI, and if necessary replace the laser with a 10 ohm, 1/2W resistor and measure the current directly (do not ground either side of this resistor ... use a scope probe on each side separately and measure the difference, with the scope probe ground lead tied to power ground).

Interface shows zeros in all places at program start

1. This is usually caused by selection of the wrong USB device number, or a bad USB cable connection between the board and the PC. Double check the cable connections, and restart the GUI program if necessary.
2. This can also be caused by an overloaded USB port. Make sure there is sufficient USB power for an extra device (Windows generally displays an error message if a USB port is overloaded).

2f channel output is extremely noisy with no laser light on detector (rare)

1. Change the bandwidth parameter on the GUI (by even one digit) and click the **Set** button below the entry text box. This resets the internal filters if they have become corrupted in some way within the FPGA.
2. If this doesn't solve the problem then click the **Reset Board** button, followed by the **Restore Factory Defaults** button. This is a laser resort to clear the problem

NOTE: Be sure to note all settings prior to this step in order to reenter them manually if you have used values that differ from the factory defaults.

Appendix B: Laser Tuning Curve Example

The C1, C2 and C3 laser scan waveform coefficients are best determined using the transmission spectrum of a suitable etalon. The figure to the right is such a spectrum recorded using a 15 mm long fused silica etalon and a 1530 nm DFB laser.

The spacing between the transmission peaks is equal to the free spectral range (FSR) of the etalon, which can be calculated from the physical length of the etalon and the known index of refraction of the etalon material at the temperature and wavelength of interest*. In this example the free spectral range is 0.228 cm^{-1} .

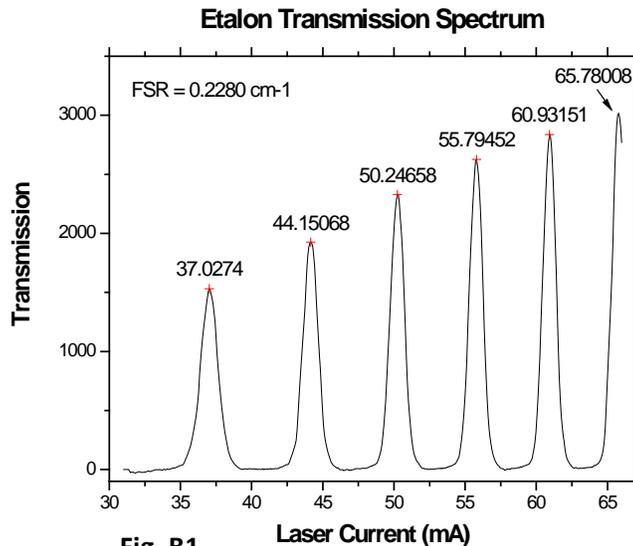


Fig. B1

To determine C1, C2 and C3, carry out the following steps

1. Scan the laser current linearly over a chosen range by setting C3 equal to 0.0 and defining a linear ramp with the C1 and C2 parameters. Record the etalon transmission spectrum as shown in the example above.
2. Locate the centers of the etalon transmission peaks to define the laser current at the peak centers. Since the spacing between the etalon transmission peaks is fixed (in cm^{-1})*, and the laser tuning is nonlinear with current (laser tunes faster as current increases), the spacing between the etalon peaks (in mA) will vary across the scan as shown (closer together at higher current levels).
3. Plot $x = \text{relative } \text{cm}^{-1} \text{ value}$ vs. $y = \text{laser current at each etalon peak}$. For this example, peak #1 coordinates are $x = 0.0 \text{ cm}^{-1}$, $y = 37.0274 \text{ mA}$, peak #2 coordinates are $x = 0.2280 \text{ cm}^{-1}$, $y = 44.15068 \text{ mA}$, etc. where the x coordinate of peak n is equal to $(n-1) \cdot \text{FSR}$.

4. Fit the resulting data with a quadratic as shown in the plot to the right. This shows the general quadratic behavior of the laser tuning curve. To get the correct values for C1, C2 and C3, one additional step is required.

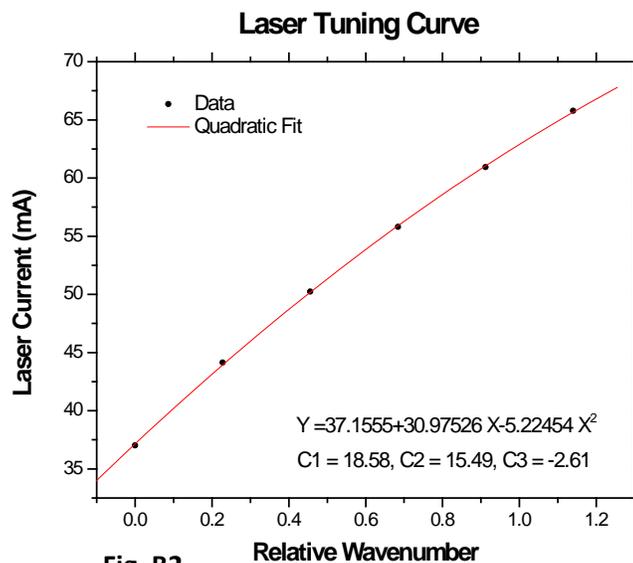


Fig. B2

To get the correct values for C1, C2 and C3, one additional step is required. The internal laser scan array is a 2048

element array, so the X-axis for the final fit must be changed from relative cm^{-1} as shown above, to a 0.0 to 1.0 range over 2047 intervals (2048 points). That is:

$$X_{\text{new}}(i) = i / 2047$$

where i runs 0 to 2047 (2048 values). A final quadratic fit of X_{new} vs. $Y = \text{mA}$ (same mA values as in steps 3/ 4) produces the final fit coefficients. For the programming GUI, divide each fit coefficient by 2 to produce the values for C1, C2 and C3. This final result is shown in Fig. B3.

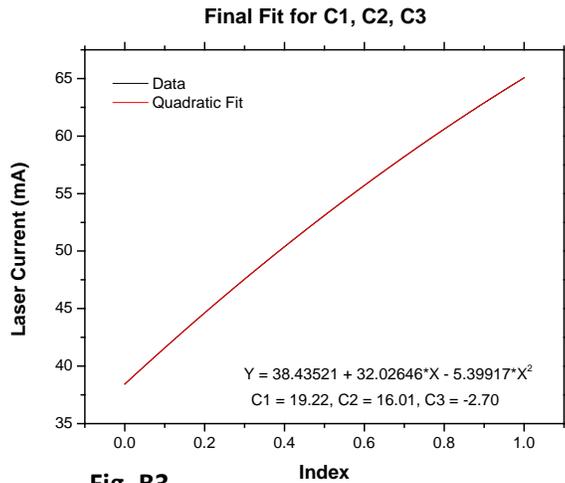


Fig. B3

Note that the original fit (Fig B2) can be extended at either end by adjusting the relative cm^{-1} range and regenerating the fit using the same coefficients (eg. offset to negative values at the low mA end of the scan, then expand the total range (linear term) to extend beyond the last fringe peak at the high mA end of the scan).

The above example showed a relative cm^{-1} scan range of 1.14 cm^{-1} (5 etalon peaks * 0.228 cm^{-1} peak spacing) using only the range from the first etalon

peak to the last peak. If this relative cm^{-1} range of 0 - 1.14 cm^{-1} is used to generate the laser scan range in mA using the fit coefficients, the range would be from 37.03 mA (peak #1) to 65.78 mA (peak #5) only. To extend the scan range down to 30 mA and up to 80 mA, for example, the constant term in the original fit (37.1555 in Fig. B2) can be changed to 30.0. Then the linear term is increased from 30.97526 to a larger value to extend the range. This is most easily done using a spreadsheet to change the linear term and observing the value that fit produces for the last point in the scan array (or just solve the quadratic for the needed value). For this example, a change in the linear term from 30.97526 to 55.0, with the constant term changed to 30.0, produces a scan from 30.0 mA to 79.75 mA. To get new values for C1, C2, and C3, repeat the final step above of creating X_{new} over the 0.0 to 1.0 range, fitting this (X) against the new range of mA values (Y) using the original fit coefficients from Fig. B2, then dividing the new fit coefficients by 2 to get final values for C1, C2 and C3 to enter into the GUI.

5. The C1, C2 and C3 coefficients can be entered into the GUI to cause the laser to scan linearly in cm^{-1} via an appropriate nonlinear (quadratic) ramp in laser current.

* The etalon FSR, to first order, is equal to $c / (2\eta L)$ where c is the speed of light, η is the material index of refraction, and L is the etalon thickness (or spacing). Both η and L are temperature dependent, and η is also wavelength dependent. Over the short tuning range of a typical DFB laser, η can be considered constant and the etalon peak spacings are constant in cm^{-1} .